

# GPSR-TARS

Congestion Aware Geographically Targeted Remote Surveillance  
for VANETs

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University of  
Nottingham  
UK | CHINA | MALAYSIA

- **NOT ASSESSED!**
- For interest only
- Work from last year
- Time for questions
- ONE



- Vehicular Ad-Hoc Networks
- Vehicles plus communication
- V2V
- V2I
- Sharing information
  - Emergency
  - Convenience
  - Pleasure



- IEEE 802.11p Wireless Access for Vehicular Environment (WAVE)<sup>1</sup>
- Multi-hop communication
- Range of 300m
- Network layer

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<sup>1</sup>Jiang and Delgrossi, “IEEE 802.11p: Towards an International Standard for Wireless Access in Vehicular Environments”.



- Highly mobile
- Wide speed range of nodes
- Routing complications
  - Direction of travel
  - 3D topology
- Plus everything else!



- Lax resource constraints
- Predictable
- Acceleration/deceleration
- Direction changes
- Maps
- Social



# Assumed Vehicular Equipment

- Computer
  - Processing
  - Storage
- Cameras
  - Dashboard, road focused (dashcams)
  - Passenger/driver facing
    - Buses
    - Taxis
    - Trams
- Global Positioning System (GPS)
- Communications
  - Wi-Fi



- Dashcams are becoming ubiquitous
  - 60% of cars in South Korea are fitted with dashcams<sup>2</sup>
- Existing infrastructure static/disconnected
- Introduce surveillance to challenging environments
- War zones
- Disasters

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<sup>2</sup>Park et al., “Motives and Concerns of Dashcam Video Sharing” .





- V3 (2005)
- LIAITHON (2012)
- REACT-DIS (2012)
- REDEC (2014)
- VoV (2014)
- HIVE (2014)
- QORE & QUALITE (2015)
- VIRTUS (2015)
- QoRA (2016)



Within a fully V2V network, for multiple remote nodes (e.g. police cars, ambulances) to get the maximum number of possible live video streams from a target region whilst they are en-route to the incident.



- Streamed multimedia is **highly** demanding
- Packet loss
- Delay
- Congestion
- Coordination



## Greedy Perimeter Stateless Routing<sup>3</sup>

Location based greedy forwarding algorithm with a fall-back to perimeter based routing if this fails.

- Requires a coordinate system
- Proactive (table-driven)
- Beacons
- Next best hop
- Low overhead
- Robust message delivery

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<sup>3</sup>Karp and Kung, "GPSR: Greedy Perimeter Stateless Routing for Wireless Networks".



## Enhanced GPSR<sup>4</sup>

Congestion mitigation extension which seeks to avoid overloading nodes.

- Monitor and share buffer capacity
- Avoid over-loading neighbours

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<sup>4</sup>Hu et al., “An enhanced GPSR routing protocol based on the buffer length of nodes for the congestion problem in VANETs”.



## Enhanced GPSR<sup>5</sup>

Uses velocity and direction to improve selection of next best hop.

- Speed and vector added to beacon
- Drastic improvements in VANETs
  - Highway
  - Urban
- Reduced delay and increased delivery

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<sup>5</sup>Bouras, Kapoulas, and Tsanai, "A GPSR Enhancement Mechanism for Routing in VANETs".



# Targeted Remote Surveillance (TARS) Module

## Overview

### Aim

To provide multiple, moving vehicles with remote, on-demand access to location based, mobile video streams.



# Targeted Remote Surveillance (TARS) Module

## Core Components

Query Mechanism

Clustering Algorithm

Dynamic Congestion Response





- Assume an existing public key infrastructure (PKI)
- Mounted tamper-proof key-store
- Authorised surveillance nodes
- Vehicles uniquely identifiable
- Encrypted streams means no data redundancy



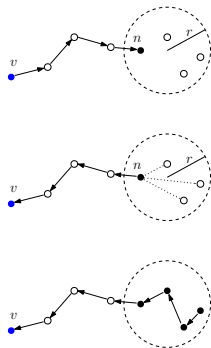
- Add support for region forwarding per CCN
- SREQ: Surveillance Request
  - Desired Location
  - Expiry Time
  - Requesting Node(s)
- Duplicate suppression
- Loop free
- Forwarded to target region

Zone $(x, y)$	Expiry	$d_0 \dots d_n$
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# Cluster Formation

- Node(s) in region receive(s) SREQ
- Cluster initialised through HELLO+
- Initial radius estimated from region density
- Streaming begins, propagated to destination node(s)



- Augment GPSR beacons
- Increase frequency
- Nodes independent
- Monitor state
- Trivial membership status changes

Zone $(x, y)$
Radius
Expiry
ID <sub>1... D </sub>
(ID, $(x, y)$ , Last Seen) <sub>1... M </sub>



$$r_i = r_{i-1} - \frac{\alpha \cdot r_{i-1} \cdot |V(G)|}{\max_{v \in V} \epsilon(v)^\beta} \quad (1)$$

- Absence of congestion
- Increase size slowly based on density
- $\delta$  and  $\gamma$  dynamically determined
- Supports competing cluster heads
- Calculation of  $\epsilon$  via e.g. Vincenty<sup>6</sup>.

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<sup>6</sup>Vincenty, "DIRECT AND INVERSE SOLUTIONS OF GEODESICS ON THE ELLIPSOID WITH APPLICATION OF NESTED EQUATIONS".

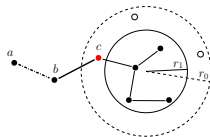


# Cluster Scaling

## Responding to Congestion

- Detection of congestion along path
- Early propagation of *future* failure
- Scale down region by factor of density
- $\alpha$  and  $\beta$  dynamically determined to promote rapid scaling
- Beacon period before further adjustment

$$r_i = r_{i-1} + \frac{\gamma \cdot r_{i-1} \cdot |V(G)|}{\max_{v \in V} \epsilon(v)^\delta} \quad (2)$$



- Simulation of Urban MObility (SUMO)<sup>7</sup>
- Highly realistic traces
- 25km<sup>2</sup> area of Nottingham city centre
- Urban scenario
- 'Typical' daily traffic



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<sup>7</sup>Krajzewicz et al., "Recent Development and Applications of SUMO - Simulation of Urban MObility".

- ns-3<sup>8</sup>
- Compared against existing work (GPSR-TARS, GPSR, AODV-L, DSDV-L)
- Increasing number of requesting nodes
- Delay
- Packet Loss
- Size of region

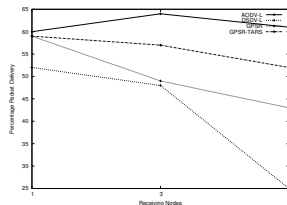
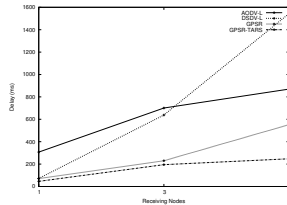
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<sup>8</sup>Riley and Henderson, "The ns-3 Network Simulator".





- GPSR & GPSR-TARS identical when  $|M|$  is 1
- When  $|M| > 1$  TARS provides better recovery
- AODV consistently higher delivery ratio!<sup>9</sup>
- $\approx 200$ ms delay for all  $D$
- Successful adaptation to congestion *but* reduced zone size



<sup>9</sup>Bala and Krishna, "Scenario Based Performance Analysis of AODV and GPSR Routing Protocols in a VANET".

- Deeper analysis
- Heterogeneous network adaptations
- Consider resource constraints
- Connectivity Aware Routing (CAR)<sup>10</sup>
- Retroactive queries
- Framework
- Prediction based dynamics
- Investigate related proposals<sup>11</sup>

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<sup>10</sup>Yang, Lim, and Agrawal, “Connectivity Aware Routing in Vehicular Networks”.

<sup>11</sup>Alsaqour et al., “Dynamic Packet Beaconing for GPSR Mobile Ad Hoc Position-based Routing Protocol Using Fuzzy Logic”.



Any Questions?

## Reminder

- Lecture tomorrow with Milena
- Think about coursework topic

